Frequency Based Fatigue

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Deterministic versus Random

Deterministic – from past measurements the future position of a satellite can be predicted with reasonable accuracy

Random – from past measurements the future position of a car can only be described in terms of probability and statistical averages





Statistics of Time Histories

- Mean or Expected Value
- Variance / Standard Deviation
- Coefficient of Variation
- Root Mean Square
- Kurtosis
- Skewness
- Crest Factor
- Irregularity Factor

Mean or Expected Value

Central tendency of the data

Mean
$$= \mu_x = \overline{x} = E(X) = \frac{\sum_{i=1}^{N} x_i}{N}$$

Variance / Standard Deviation

Dispersion of the data

$$\operatorname{Var}(X) = \frac{\sum_{i=1}^{N} (x_i - \overline{X})^2}{N}$$

Standard deviation

$$\sigma_x = \sqrt{Var(X)}$$

Coefficient of Variation

$$\text{COV} = \frac{\sigma_x}{\mu_x}$$

Useful to compare different dispersions

$$\begin{array}{ll} \mu = 10 & \mu = 100 \\ \sigma = 1 & \sigma = 10 \\ \text{COV} = 0.1 & \text{COV} = 0.1 \end{array}$$



$$RMS = \frac{\sqrt{\sum_{i=1}^{N} x_i^2}}{N}$$

The rms is equal to the standard deviation when the mean is 0

Skewness

Skewness is a measure of the asymmetry of the data around the sample mean. If skewness is negative, the data are spread out more to the left of the mean than to the right. If skewness is positive, the data are spread out more to the right. The skewness of the normal distribution (or any perfectly symmetric distribution) is zero.

Skewness(X) =
$$\frac{\sum_{i=1}^{N} (x_i - \overline{x})^3}{N\sigma^3}$$

Kurtosis

Kurtosis is a measure of how outlier-prone a distribution is. The kurtosis of the normal distribution is 3. Distributions that are more outlier-prone than the normal distribution have kurtosis greater than 3; distributions that are less outlier-prone have kurtosis less than 3.

Kurtosis(X) =
$$\frac{\sum_{i=1}^{N} (x_i - \overline{x})^4}{N\sigma^4}$$

Crest Factor

The crest factor is the ration of the peak (maximum) value to the root-mean-square (RMS) value. A sine wave has a crest factor of 1.414.



IF \rightarrow 0 is wide band signal

Time Domain Nomenclature

- Random
- Stochastic
- Stationary
- Non-stationary
- Gaussian
- Narrow-band
- Wide-band

Random

The instantaneous value can not be predicted at any future time.

Stochastic

Stochastic processes provide suitable models for physical systems where the phenomena is governed by probabilities.

Stationary



The properties computed over short time intervals, t + Δ t, do not significantly vary from each other





Gaussian

Normally distributed around the mean







Frequency Domain Nomenclature

Fourier Nyquist frequency Aliasing Anit-aliasing filter FFT **Inverse FFT** Autospectral density **Transfer Function**

Fourier 1768 - 1830



Fourier studied the mathematical theory of heat conduction. He established the partial differential equation governing heat diffusion and solved it by using infinite series of trigonometric functions.

Fourier Series

$$X(t) = a_{o} + \sum_{k=1}^{\infty} a_{k} \sin(k\omega_{o}t) + b_{k} \cos(k\omega_{o}t)$$
$$X(t) = c_{o} + \sum_{k=1}^{\infty} c_{k} \cos(k\omega_{o}t + \theta_{k})$$

$$X(t) = \sum_{k=-\infty}^{\infty} X_{s}[k]e^{jk\omega_{o}t}$$

a_k, b_k, c_k, X_S[k] are Fourier coefficients

frequency, magnitude, and phase are all described by the coefficients



What Δt should be used for sampling the data?

Aliasing



Both signals have the same digital samples.



Sample at 2 times the frequency of interest







The area under each spike represents the magnitude of the sine wave at that frequency.

The magnitude of the FFT depends on the frequency window Δf .

Fast Fourier Transform - FFT



Fast Fourier Transform - FFT





Autospectral Density

Function	Units	
Time History	EU	X(n)
Linear Spectrum	EU	S(n) = DFT(X(n))
AutoPower	EU^2	$AP(n) = S(n) \cdot S(n)$
PSD	(EU^2)/Hz	$PSD(n) = AP(n) / (W_f \cdot \Delta f)$
ESD	(EU^2*sec)/Hz	$ESD(n) = AP(n) \cdot T / (W_{f} \cdot \Delta f)$

Calculating Autospectral Density



N_D Block size

$$S(f_k) = \frac{1}{n_D N_D \Delta t} \sum_{i=1}^{n_D} |X(f_k)|^2$$

Magnitude only no phase information

Power Spectral Density - PSD





Log Magnitude-Linear-Strain_c56



Sometimes called Amplitude Spectral Density





Frequency Domain Limitations

Non-stationary signals







Transfer Function



Frequency Based Fatigue



- Stationary Loading
 - Wind
 - Sea State
 - Vibration

Assumptions

Random Gaussian Stationary













$$\Delta S_i - \frac{\delta S}{2}$$
 and $\Delta S_i + \frac{\delta S}{2}$ is $P(\Delta S_i) = p(\Delta S_i) \delta S$



Cycles at level i
$$n_i = p(\Delta S_i) \delta S N_T$$

Total cycles $N_T = E(P) T$
 t Total time
Fatigue life $N_f(\Delta S_i) = \left(\frac{\Delta S_i}{2S_f}\right)^{\frac{1}{b}}$
Fatigue Damage $D = \sum_{i=1}^{N} \frac{n_i}{N_f(\Delta S_i)} = E(P)T\delta S(2S_f)^{\frac{1}{b}} \sum_{i=1}^{N} \frac{p(\Delta S_i)}{(\Delta S_i)^{\frac{1}{b}}}$

Fatigue damage is determined by p(ΔS_i)

Narrow Band Solution



Rayleigh distribution

$$p(\Delta S) = \frac{\Delta S}{4m_0} \exp\left[-\frac{\Delta S^2}{8m_0}\right]$$

 $\text{IF} \rightarrow 1$ is narrow band signal

 $\text{IF} \rightarrow 0$ is wide band signal

This wide band signal has the same peak distribution as this narrow band signal



$$p(\Delta S) = f(m_0, m_1, m_2, m_4)$$

$$p(\Delta S) = \frac{\frac{D_1}{Q} \exp\left(-\frac{Z}{Q}\right) + \frac{D_2}{R^2} \exp\left(-\frac{Z^2}{R^2}\right) + D_3 Z \exp\left(-\frac{Z^2}{2}\right)}{2\sqrt{m_0}}$$







Frequency (Hz)



Relative Fatigue Estimates

	Dirlik	Rayleigh
SN Slope	$\frac{N_{PSD}}{N_{TH}}$	$\frac{N_{PSD}}{N_{TH}}$
10	371	109
5	6.6	1.9
3	1.8	0.5











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